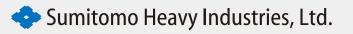
# Sumitomo Drive Technologies



# Drive Solutions for AGV/AMR



No.L2055E-3



# Combination of three smart components.

# Creating a compact, integrated and intelligent solution of: **Gear + Servo Motor + Drive for AGV/AMRs in one package!**

The necessary components are packaged together, making it easy to design and manufacture AGV/AMRs.



# Features

#### Compact

The in-wheel structure realizes space-saving in AGV/AMRs. It contributes to lower the height of AGV/AMRs and more effective use of internal space.

Compact Drive with small installation area are available for ECO-S, ECO-M, and PRO-M.

#### Capable of supporting a wide range of payloads

Multiple sizes and reduction ratios are available, allowing you to design AGVs and AMRs that support a wide range of payloads.

#### High performance servo control

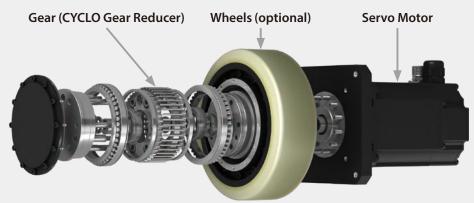
High speed, high precision, and high responsiveness are achieved by high-resolution servo control (the drive's internal control resolution is 16384 inc/rev).

The system can operate at an industry-leading max speed of 2.0m/s and max acceleration of 1.0m/s<sup>2</sup>.

#### **Superior safety**

The CYCLO Gear Reducer principle with excellent impact resistance is used for the gear part.

With a focus on compliance with "ISO 3691-4: 2020 Industrial Trucks - Safety Requirements and Verification" and "JIS D 6802: 2022 Automated Guided Vehicles and Automated Guided Vehicle Systems - Safety Requirements and Verification", an optional version with STO (Safe Torque Off) capabilities is also available.



# **Example of AGV/AMR Configuration**

This is an example configuration of an AGV/AMR drive system. Depending on configuration conditions, it is possible to support a payload of over 3,000 kg.

We will propose the optimal smartris to maximize AGV/AMR performance.

kg	800	1100	1800	3000
	2	2	2	2
	4	4	4	4
kg	125	125	125	250
m/s	2.00	2.00	2.00	1.78
m/s²	1.0	1.0	1.0	1.0
mm	180	200	200	250
N∙m	15.8	24.0	39.3	80.9
w	392	537	878	1320
	kg m/s m/s² mm N·m	2 4 4 kg 125 m/s 2.00 m/s² 1.0 mm 180 N·m 15.8	C         2         2           2         2         2           4         4         4           kg         125         125           m/s         2.00         2.00           m/s²         1.0         1.0           mm         180         200           N·m         15.8         24.0	2         2         2         2           4         4         4           kg         125         125         125           m/s         2.00         2.00         2.00           m/s <sup>2</sup> 1.0         1.0         1.0           mm         180         200         200           N·m         15.8         24.0         39.3

smartris

		•							
Туре	E	0	PRO						
Size	S M		М	L					
Gearmotor Frame Size	5087E	5097E	5097P	5107P					
Reduction Ratio	21	21	22	22					

Note: This is the case for the drive with the input voltage specification of 48 VDC. With the Compact Drive with the input voltage specification of 24 VDC, the maximum running speed is 1/2.



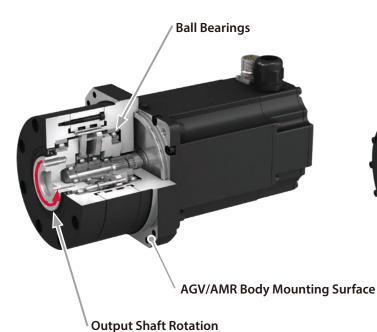
### Gearmotor (Gear, Servo Motor) Specifications

#### **ECO Type**

- Output Shaft Rotation
- For Light Payload Machines



- Ring Gear Housing Rotation
- High Radial Payload



AGV/AMR Body Mounting Surface (behind the flange)

**Tapered Roller Bearings** 

(wheel mounting surface)

Ring Gear Housing Rotation (wheel mounting surface)

Туре			ECO					PRO				
Size Gearmotor Frame Size			S M		м		L					
		5087E 5097E		5097P		5107P						
Input Voltage of the Drive	VDC	24 o		or 48		24 or 48		48				
Allowable Radial Load per Driving Wheel Note: 1	Ν	1500 3000			6500		10000					
Reduction Ratio		21	25	29	21	25	29	22	26	22	26	30
Max Motor Speed Note: 2	r/min		4500			4500		4500		3000		
Max Wheel Speed Note: 2	r/min	214	180	155	214	180	155	205	173	136	115	100
Rated Wheel Torque	N∙m	16.0	18.9	18.9	39.3	40.4	40.5	39.3	40.4	84.7	87.5	80.3
Peak Wheel Torque (2s)	N∙m	61.9	73.7	84.8	145	179	207	145	179	294	360	246
Ambient Temperature	°C	-10 to +40 (0 to +40 if fitted with optional wheels)			-10 to +40 (0 to +40 if fitted with optional wheels)			heels)				
Ambient Humidity	%RH	85 or less (20 to 80 if fitted with optional wheels) with no condensation			) 85 or less (20 to 80 if fitted with option wheels) with no condensation			•				
Protection Class		IP54			IP54							
Thermal Class		Motor: 155 (F), Brake: F			Motor: 155 (F), Brake: F							
Output Type			0	utput Sha	aft Rotatio	on			Ring Gea	r Housing	g Rotatior	า

Note: 1. Allowable radial load of ECO Type is a value at the position inside the output shaft end face.

Allowable radial load of PRO Type is a value at the center of the gear part.

2. With the Compact Drive with the input voltage specification of 24 VDC, the maximum rotation speed of the motor and the wheel is 1/2.

3. The motor/brake power cable brakes will be shipped attached to the motor via a cable gland. (with cable length: 1 m)



### **Standard Specifications**

Rotation Feedback		Resolver with a resolution of 4096 Note: 1 (provided with a 1 m cable)
Brake Note: 2		
Specification		PM brake (for holding)
Release Voltage	VDC	24±10%
Current	ADC	ECO-S 0.45, ECO-M/PRO-M/PRO-L 0.83
Wheel		The wheels are to be prepared by the customer, but they can also be provided by the manufacturer as an option.

# **Options**

Rotation Feedback Note: 3	Absolute encoder with	Absolute encoder with a resolution 4096 Note: 1 (provided with a 1 m cable) Absolute encoder with optional safety features with a resolution of 4096 Note: 1 (provided with a 1 m cable)								
	Absolute encoder with c									
Wheels Note: 4	Wheels with urethane	Wheels with urethane tires								
Туре	1	ECO	PRO							
Size	s	м	м	L						
Gearmotor Frame Size	5087E	5097E	5097P	5107P						
Wheel Size	Ø180×65	Ø200×65	Ø200×66	Ø250×75						
Allowable Radial Load per Driving Wheel $^{\tt Note:S}$ N	1500	3000	6500	10000						
Allowable Speed m/	<b>/s</b> 2.00	2.00	2.00	1.78						
Tire Material	Urethane har	dness 90 (JIS A)	Urethane hardness 90 (JIS A)							
Accessories Note: 6	M6 bolts 10pcs M6 washers 10pcs	M8 bolts 8pcs M8 washers 8pcs	M5 bolts 12pcs M5 washers 12pcs O-ring G-140 1pcs	M6 bolts 12pcs M6 washers 12pcs O-ring AS568-261 1pcs						

Note: 1. The control resolution inside the drive is 16384 inc/rev.

2. The brake is for holding when parked and cannot be used for braking. Contact us if you wish to use the product for braking, such as an emergency stop.

3. Select an absolute encoder-compatible drive.

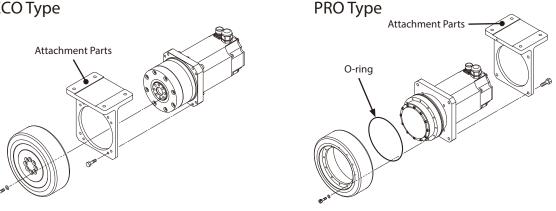
4. Intended for use in indoor area with smooth concrete surface and good electrical discharge properties. Cannot be used on wet, oily or dirty surfaces.

5. The allowable radial load is the same as for the standard specification (without wheels).

6. Wheels and accessories are shipped together with but not assembled to the gearmotor.

### How to Install the Product on an AGV/AMR

#### **ECO** Type



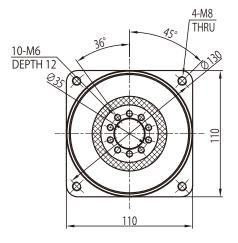
- For the ECO Type, the gearmotor must be installed on the AGV/AMR body before the wheels are installed.
- Attachment parts are not included.
- If the wheels are prepared by the customer, please prepare the bolts, washers, and O-rings by yourself. Optional wheels will be provided with all the wheel accessories listed in the option column.
- For details such as the tightening torque, refer to the instruction manual.

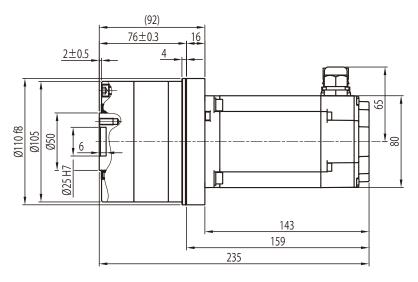


# **Dimensional Drawing of ECO Type**



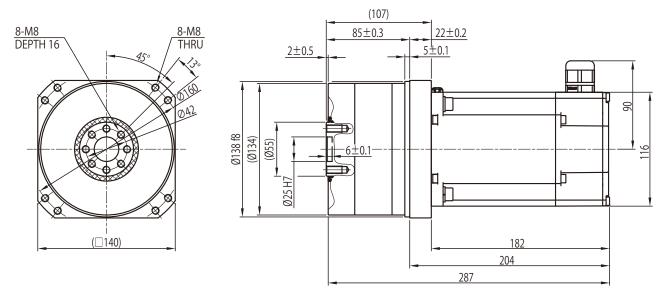
#### ECO-S/5087E





Mass: 5.6kg

#### ECO-M/5097E



Mass: 11.3kg

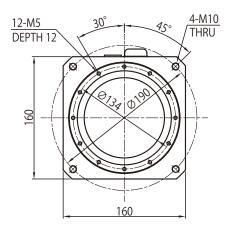
Note) 1. The wheels need to be prepared by the customer. but they can also be provided by the manufacturer as an option. 2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.



# **Dimensional Drawing of PRO Type**



PRO-M/5097P

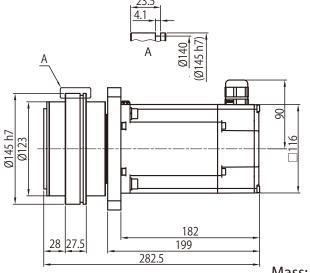


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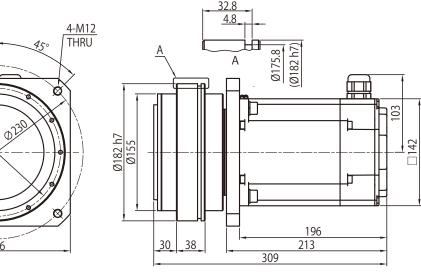
#### PRO-L/5107P

12-M6

DEPTH 12

196





Mass: 24.5kg

#### Recommended Inner Dimensions of Processed Wheel for Mounting

196

<u>Z</u>		e. Frame				O-ring (Nitrile Rubber)		
	Size	Size	Spigot Width	Spigot Inner Diameter Y	O-ring Inner Diameter Y'	Part Number	Wire Diameter × Inner Diameter	
	М	5097P	6	145	145.5	G-140	3.1×139.4	
AYA Ø	L	5107P	8	182	182.5	AS568-261	3.53×171.04	

Note) 1. The wheels need to be prepared by the customer. but they can also be provided by the manufacturer as an option.

2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.

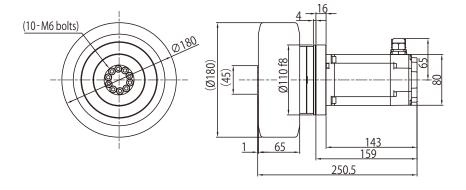
3. Mount O-ring (to be prepared by the customer) to prevent molybdenum disulfide grease (an anti-fretting agent) applied to the spigot part from leaking outside through any gaps.

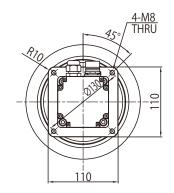


# Dimensional Drawing of ECO Type (with optional wheels)



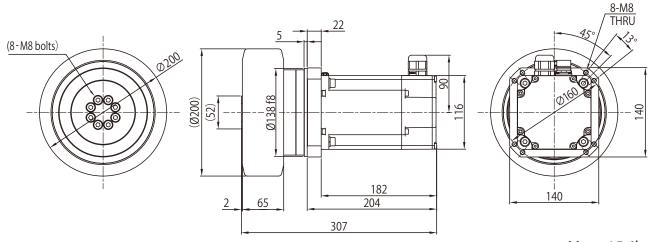
### ECO-S/5087E





Mass: 9.3kg

ECO-M/5097E



Mass: 15.6kg

Note) 1. The wheels are shipped together with the tightening bolts and washers without being assembled to the gearmotor.

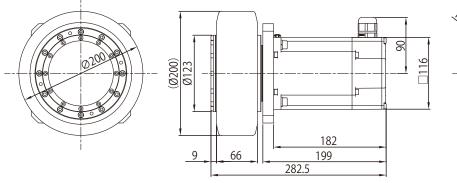
2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.

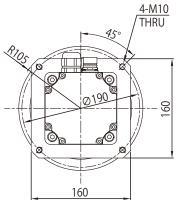


# Dimensional Drawing of PRO Type (with optional wheels)



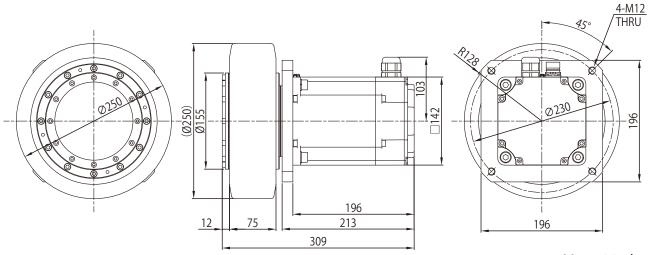
#### PRO-M/5097P





Mass: 17.5kg

PRO-L/5107P



Mass: 29.7kg

Note) 1. The wheels are shipped together with the tightening bolts, O-ring and washers without being assembled to the gearmotor. 2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.



# **Drive Dimensions and Specifications**

Optical drives for AGV/AMR are prepared.

- Gain control adjusted for common AGV/AMR applications
- Implements CANopen (DS402) or RS-485 Modbus RTU
- Equipped with emergency stop input function

Туре		E	CO	PRO						
Size		S	М	М	L					
Gearmotor Frame Size		5087E	5097E	5097P	5107P					
		Compact D	Drive AG210	Compact Drive AG210	New J.D. S. AC110 Note:1					
Drive Nomenclature		Normal D	rive AG110	Normal Drive AG110	Normal Drive AG110 Note: 1					
Rated Current	Arms	12.5	25.8	25.8	35.8					
Peak Current (2sec)	Arms	41.0	96.3	96.3	136.2					
Peak Current (10sec)	Arms	24.9	57.5	57.5	81.3					
Input Voltage of the Drive	VDC	Select Compact Drive 24 (20-60) or 48 (30-60), Normal Drive 48 (30-60)								
Rotation Feedback		Resolver (absolute encoder is available as an option)								
Communication Method		Select CANopen (DS402) or RS-485 Modbus RTU Note: 2								
Control Mode		Speed control, torque control								
Digital Input		Two inputs <sup>Note: 3</sup> Photocoupler insulation (24V±20%, 7mA, with an input impedance of 3kΩ) can be used with either sink logic or source logic								
Digital Output		Two outputs Note: 3 Photocoupler insulation (24V±20%, 100mA) can be used with sink logic or source logic								
Safety Function		Select with STO or without STO (Safe Torque Off ) capabilities								
Protection Class			Compact Drive IP2	0, Normal Drive IP54						
Certification		CE, UL, KC (U	CE, UL, KC (UL and KC certification for Compact Drive are in-process of acquisition) Note: 5							

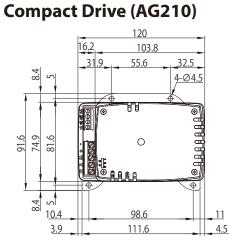
Note: 1. For PRO-L/5107P, only Normal Drive can be connected.

2. Contact us about analog mode applications.

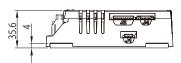
- 3. Four points can be used in analog mode.
- Power cable is not supplied with the product.
   Control cable (0.4m long) is supplied with the Compact Drive.

Control cable is not supplied with the Normal Drive.

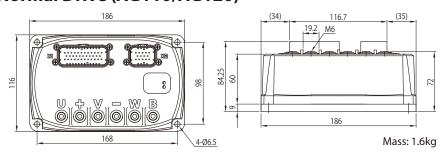
5. If UL or KC compliance is required, be sure to specify when ordering.



#### Normal Drive (AG110/AG120)



Mass: 0.3kg







# Controller

The controller is not included in the smartris package.

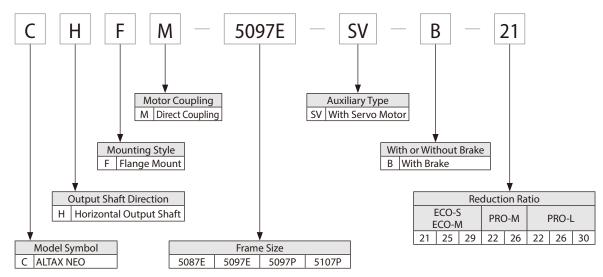
The product has been tested and verified to work with the following controllers in communication mode.

- BlueBotics/Autonomous navigation system ANT lite<sup>+</sup> (CANopen)
- Hitachi Industrial Equipment Systems Co., Ltd./Laser positioning system ICHIDAS, industrial controller HX series (RS-485 Modbus RTU)

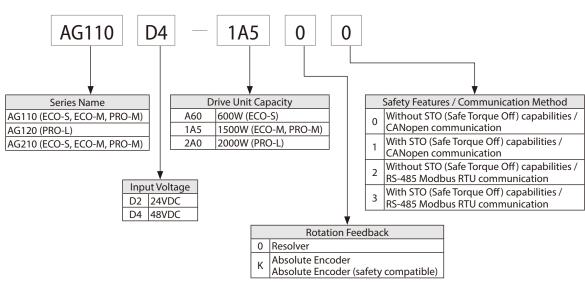
Contact us for further details.

# Nomenclature

Gearmotor (Gear + Servo Motor)



Drive



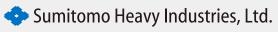




Smartris products use servo motors provided by Lafert S.p.A., an Italian industrial motor manufacturer that became part of the Sumitomo Heavy Industries Group in 2018. Lafert S.p.A. offers a wide range of electronic and control products, including high-efficiency magnet motors, induction motors, and servo motor drives, to meet customer needs in the fields of automation and energy.

Sumitomo Heavy Industries Group will continue to provide drive solutions that meet the sophisticated needs of society by mutually utilizing and integrating the technologies and knowledge of gearmotors, electronics, and control.

Specifications, dimensions, and other items are subject to change without prior notice.



**Power Transmission & Controls Group** Headquarter ThinkPark Tower, 1-1 Osaki 2-chome, Shinagawa-ku, Tokyo 141-6025, Japan

