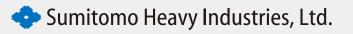
Sumitomo Drive Technologies



Drive Solutions for AGV/AMR



No.L2055E-3



Combination of three smart components.

Creating a compact, integrated and intelligent solution of: **Gear + Servo Motor + Drive for AGV/AMRs in one package!**

The necessary components are packaged together, making it easy to design and manufacture AGV/AMRs.



Features

Compact

The in-wheel structure realizes space-saving in AGV/AMRs. It contributes to lower the height of AGV/AMRs and more effective use of internal space.

Compact Drive with small installation area are available for ECO-S, ECO-M, and PRO-M.

Capable of supporting a wide range of payloads

Multiple sizes and reduction ratios are available, allowing you to design AGVs and AMRs that support a wide range of payloads.

High performance servo control

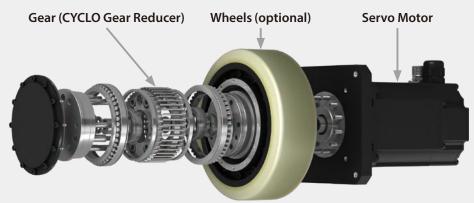
High speed, high precision, and high responsiveness are achieved by high-resolution servo control (the drive's internal control resolution is 16384 inc/rev).

The system can operate at an industry-leading max speed of 2.0m/s and max acceleration of 1.0m/s².

Superior safety

The CYCLO Gear Reducer principle with excellent impact resistance is used for the gear part.

With a focus on compliance with "ISO 3691-4: 2020 Industrial Trucks - Safety Requirements and Verification" and "JIS D 6802: 2022 Automated Guided Vehicles and Automated Guided Vehicle Systems - Safety Requirements and Verification", an optional version with STO (Safe Torque Off) capabilities is also available.



Example of AGV/AMR Configuration

This is an example configuration of an AGV/AMR drive system. Depending on configuration conditions, it is possible to support a payload of over 3,000 kg.

We will propose the optimal smartris to maximize AGV/AMR performance.

| kg | 800 | 1100 | 1800 | 3000 |
|------|--------------------------------|--|--|--|
| | 2 | 2 | 2 | 2 |
| | 4 | 4 | 4 | 4 |
| kg | 125 | 125 | 125 | 250 |
| m/s | 2.00 | 2.00 | 2.00 | 1.78 |
| m/s² | 1.0 | 1.0 | 1.0 | 1.0 |
| mm | 180 | 200 | 200 | 250 |
| N∙m | 15.8 | 24.0 | 39.3 | 80.9 |
| w | 392 | 537 | 878 | 1320 |
| | kg m/s m/s² mm N·m | 2 4 4 kg 125 m/s 2.00 m/s² 1.0 mm 180 N·m 15.8 | C 2 2 2 2 2 4 4 4 kg 125 125 m/s 2.00 2.00 m/s² 1.0 1.0 mm 180 200 N·m 15.8 24.0 | 2 2 2 2 4 4 4 kg 125 125 125 m/s 2.00 2.00 2.00 m/s ² 1.0 1.0 1.0 mm 180 200 200 N·m 15.8 24.0 39.3 |

smartris

| | | • | | | | | | | |
|----------------------|-------|-------|-------|-------|--|--|--|--|--|
| Туре | E | 0 | PRO | | | | | | |
| Size | S M | | М | L | | | | | |
| Gearmotor Frame Size | 5087E | 5097E | 5097P | 5107P | | | | | |
| Reduction Ratio | 21 | 21 | 22 | 22 | | | | | |

Note: This is the case for the drive with the input voltage specification of 48 VDC. With the Compact Drive with the input voltage specification of 24 VDC, the maximum running speed is 1/2.



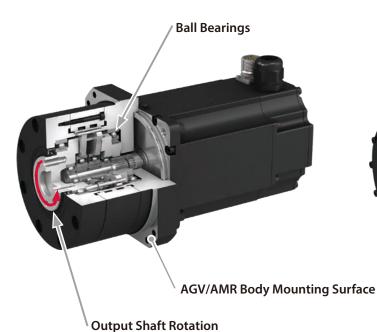
Gearmotor (Gear, Servo Motor) Specifications

ECO Type

- Output Shaft Rotation
- For Light Payload Machines



- Ring Gear Housing Rotation
- High Radial Payload



AGV/AMR Body Mounting Surface (behind the flange)

Tapered Roller Bearings

(wheel mounting surface)

Ring Gear Housing Rotation (wheel mounting surface)

| Туре | | | ECO | | | | | PRO | | | | |
|---|-------|--|------|-----------|---|----------|-------|--------|----------|-----------|------------|------|
| Size Gearmotor Frame Size | | | S M | | м | | L | | | | | |
| | | 5087E 5097E | | 5097P | | 5107P | | | | | | |
| Input Voltage of the Drive | VDC | 24 o | | or 48 | | 24 or 48 | | 48 | | | | |
| Allowable Radial Load per Driving Wheel Note: 1 | Ν | 1500 3000 | | | 6500 | | 10000 | | | | | |
| Reduction Ratio | | 21 | 25 | 29 | 21 | 25 | 29 | 22 | 26 | 22 | 26 | 30 |
| Max Motor Speed Note: 2 | r/min | | 4500 | | | 4500 | | 4500 | | 3000 | | |
| Max Wheel Speed Note: 2 | r/min | 214 | 180 | 155 | 214 | 180 | 155 | 205 | 173 | 136 | 115 | 100 |
| Rated Wheel Torque | N∙m | 16.0 | 18.9 | 18.9 | 39.3 | 40.4 | 40.5 | 39.3 | 40.4 | 84.7 | 87.5 | 80.3 |
| Peak Wheel Torque (2s) | N∙m | 61.9 | 73.7 | 84.8 | 145 | 179 | 207 | 145 | 179 | 294 | 360 | 246 |
| Ambient Temperature | °C | -10 to +40 (0 to +40 if fitted with optional wheels) | | | -10 to +40 (0 to +40 if fitted with optional wheels) | | | heels) | | | | |
| Ambient Humidity | %RH | 85 or less (20 to 80 if fitted with optional wheels) with no condensation | | |) 85 or less (20 to 80 if fitted with option wheels) with no condensation | | | • | | | | |
| Protection Class | | IP54 | | | IP54 | | | | | | | |
| Thermal Class | | Motor: 155 (F), Brake: F | | | Motor: 155 (F), Brake: F | | | | | | | |
| Output Type | | | 0 | utput Sha | aft Rotatio | on | | | Ring Gea | r Housing | g Rotatior | า |

Note: 1. Allowable radial load of ECO Type is a value at the position inside the output shaft end face.

Allowable radial load of PRO Type is a value at the center of the gear part.

2. With the Compact Drive with the input voltage specification of 24 VDC, the maximum rotation speed of the motor and the wheel is 1/2.

3. The motor/brake power cable brakes will be shipped attached to the motor via a cable gland. (with cable length: 1 m)



Standard Specifications

| Rotation Feedback | | Resolver with a resolution of 4096 Note: 1 (provided with a 1 m cable) |
|-------------------|-----|--|
| Brake Note: 2 | | |
| Specification | | PM brake (for holding) |
| Release Voltage | VDC | 24±10% |
| Current | ADC | ECO-S 0.45, ECO-M/PRO-M/PRO-L 0.83 |
| Wheel | | The wheels are to be prepared by the customer, but they can also be provided by the manufacturer as an option. |

Options

| Rotation Feedback Note: 3 | Absolute encoder with | Absolute encoder with a resolution 4096 Note: 1 (provided with a 1 m cable) Absolute encoder with optional safety features with a resolution of 4096 Note: 1 (provided with a 1 m cable) | | | | | | | | |
|---|------------------------------------|---|---|---|--|--|--|--|--|--|
| | Absolute encoder with c | | | | | | | | | |
| Wheels Note: 4 | Wheels with urethane | Wheels with urethane tires | | | | | | | | |
| Туре | 1 | ECO | PRO | | | | | | | |
| Size | s | м | м | L | | | | | | |
| Gearmotor Frame Size | 5087E | 5097E | 5097P | 5107P | | | | | | |
| Wheel Size | Ø180×65 | Ø200×65 | Ø200×66 | Ø250×75 | | | | | | |
| Allowable Radial Load per Driving Wheel $^{\tt Note:S}$ N | 1500 | 3000 | 6500 | 10000 | | | | | | |
| Allowable Speed m/ | /s 2.00 | 2.00 | 2.00 | 1.78 | | | | | | |
| Tire Material | Urethane har | dness 90 (JIS A) | Urethane hardness 90 (JIS A) | | | | | | | |
| Accessories Note: 6 | M6 bolts 10pcs M6 washers 10pcs | M8 bolts 8pcs M8 washers 8pcs | M5 bolts 12pcs M5 washers 12pcs O-ring G-140 1pcs | M6 bolts 12pcs M6 washers 12pcs O-ring AS568-261 1pcs | | | | | | |

Note: 1. The control resolution inside the drive is 16384 inc/rev.

2. The brake is for holding when parked and cannot be used for braking. Contact us if you wish to use the product for braking, such as an emergency stop.

3. Select an absolute encoder-compatible drive.

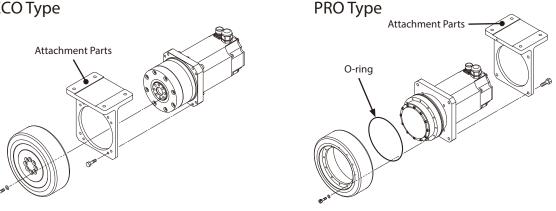
4. Intended for use in indoor area with smooth concrete surface and good electrical discharge properties. Cannot be used on wet, oily or dirty surfaces.

5. The allowable radial load is the same as for the standard specification (without wheels).

6. Wheels and accessories are shipped together with but not assembled to the gearmotor.

How to Install the Product on an AGV/AMR

ECO Type



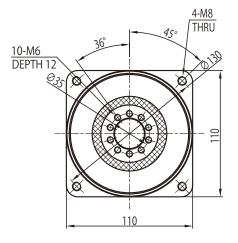
- For the ECO Type, the gearmotor must be installed on the AGV/AMR body before the wheels are installed.
- Attachment parts are not included.
- If the wheels are prepared by the customer, please prepare the bolts, washers, and O-rings by yourself. Optional wheels will be provided with all the wheel accessories listed in the option column.
- For details such as the tightening torque, refer to the instruction manual.

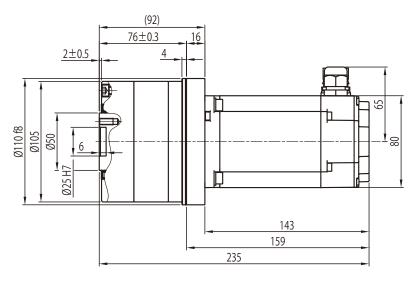


Dimensional Drawing of ECO Type



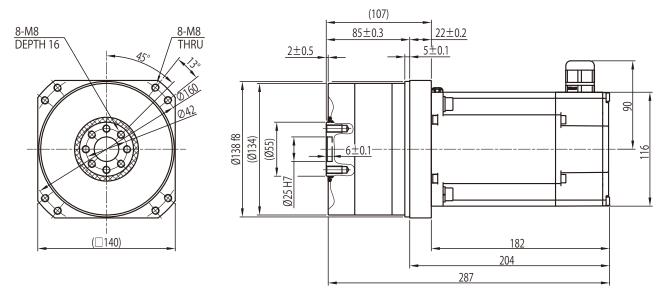
ECO-S/5087E





Mass: 5.6kg

ECO-M/5097E



Mass: 11.3kg

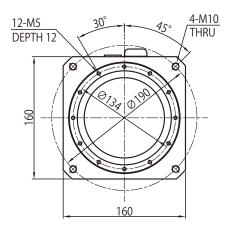
Note) 1. The wheels need to be prepared by the customer. but they can also be provided by the manufacturer as an option. 2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.



Dimensional Drawing of PRO Type



PRO-M/5097P

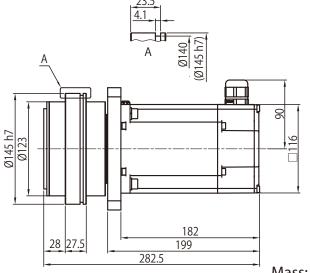


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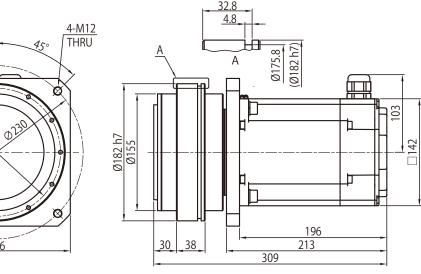
PRO-L/5107P

12-M6

DEPTH 12

196





Mass: 24.5kg

Recommended Inner Dimensions of Processed Wheel for Mounting

196

| <u>Z</u> | | e. Frame | | | | O-ring (Nitrile Rubber) | | |
|----------|------|----------|--------------|----------------------------|-----------------------------|-------------------------|-----------------------------------|--|
| | Size | Size | Spigot Width | Spigot Inner Diameter Y | O-ring Inner Diameter Y' | Part Number | Wire Diameter × Inner Diameter | |
| | М | 5097P | 6 | 145 | 145.5 | G-140 | 3.1×139.4 | |
| AYA Ø | L | 5107P | 8 | 182 | 182.5 | AS568-261 | 3.53×171.04 | |

Note) 1. The wheels need to be prepared by the customer. but they can also be provided by the manufacturer as an option.

2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.

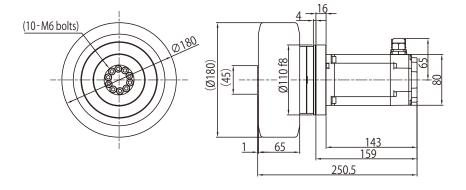
3. Mount O-ring (to be prepared by the customer) to prevent molybdenum disulfide grease (an anti-fretting agent) applied to the spigot part from leaking outside through any gaps.

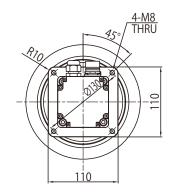


Dimensional Drawing of ECO Type (with optional wheels)



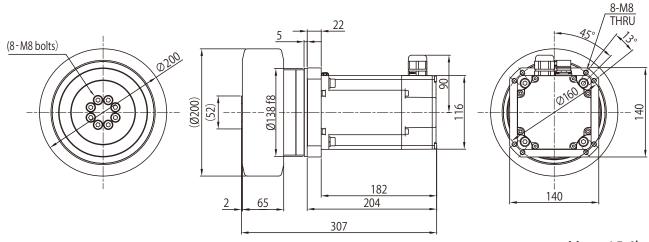
ECO-S/5087E





Mass: 9.3kg

ECO-M/5097E



Mass: 15.6kg

Note) 1. The wheels are shipped together with the tightening bolts and washers without being assembled to the gearmotor.

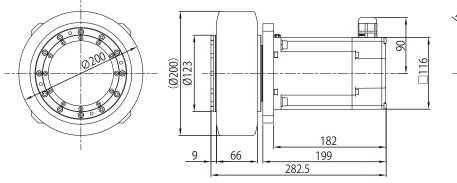
2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.

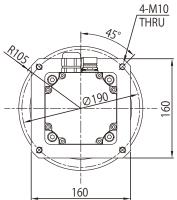


Dimensional Drawing of PRO Type (with optional wheels)



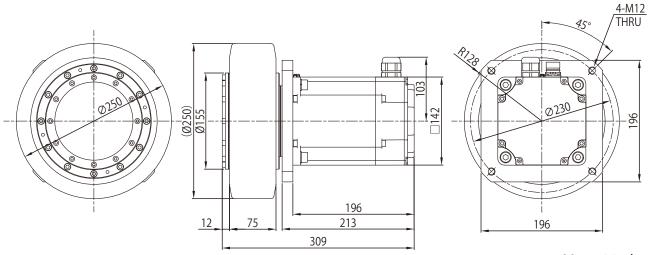
PRO-M/5097P





Mass: 17.5kg

PRO-L/5107P



Mass: 29.7kg

Note) 1. The wheels are shipped together with the tightening bolts, O-ring and washers without being assembled to the gearmotor. 2. Shown are the dimensions where a resolver is used for rotation feedback. Inquire for dimensions with an absolute encoder.



Drive Dimensions and Specifications

Optical drives for AGV/AMR are prepared.

- Gain control adjusted for common AGV/AMR applications
- Implements CANopen (DS402) or RS-485 Modbus RTU
- Equipped with emergency stop input function

| Туре | | E | CO | PRO | | | | | | |
|----------------------------|------|---|--|----------------------|----------------------------|--|--|--|--|--|
| Size | | S | М | М | L | | | | | |
| Gearmotor Frame Size | | 5087E | 5097E | 5097P | 5107P | | | | | |
| | | Compact D | Drive AG210 | Compact Drive AG210 | New J.D. S. AC110 Note:1 | | | | | |
| Drive Nomenclature | | Normal D | rive AG110 | Normal Drive AG110 | Normal Drive AG110 Note: 1 | | | | | |
| Rated Current | Arms | 12.5 | 25.8 | 25.8 | 35.8 | | | | | |
| Peak Current (2sec) | Arms | 41.0 | 96.3 | 96.3 | 136.2 | | | | | |
| Peak Current (10sec) | Arms | 24.9 | 57.5 | 57.5 | 81.3 | | | | | |
| Input Voltage of the Drive | VDC | Select Compact Drive 24 (20-60) or 48 (30-60), Normal Drive 48 (30-60) | | | | | | | | |
| Rotation Feedback | | Resolver (absolute encoder is available as an option) | | | | | | | | |
| Communication Method | | Select CANopen (DS402) or RS-485 Modbus RTU Note: 2 | | | | | | | | |
| Control Mode | | Speed control, torque control | | | | | | | | |
| Digital Input | | Two inputs ^{Note: 3} Photocoupler insulation (24V±20%, 7mA, with an input impedance of 3kΩ) can be used with either sink logic or source logic | | | | | | | | |
| Digital Output | | Two outputs Note: 3 Photocoupler insulation (24V±20%, 100mA) can be used with sink logic or source logic | | | | | | | | |
| Safety Function | | Select with STO or without STO (Safe Torque Off) capabilities | | | | | | | | |
| Protection Class | | | Compact Drive IP2 | 0, Normal Drive IP54 | | | | | | |
| Certification | | CE, UL, KC (U | CE, UL, KC (UL and KC certification for Compact Drive are in-process of acquisition) Note: 5 | | | | | | | |

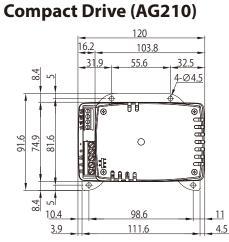
Note: 1. For PRO-L/5107P, only Normal Drive can be connected.

2. Contact us about analog mode applications.

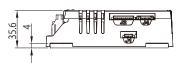
- 3. Four points can be used in analog mode.
- Power cable is not supplied with the product.
 Control cable (0.4m long) is supplied with the Compact Drive.

Control cable is not supplied with the Normal Drive.

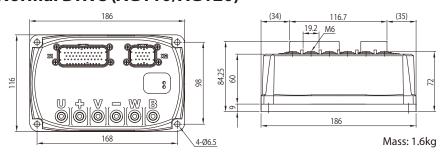
5. If UL or KC compliance is required, be sure to specify when ordering.



Normal Drive (AG110/AG120)



Mass: 0.3kg







Controller

The controller is not included in the smartris package.

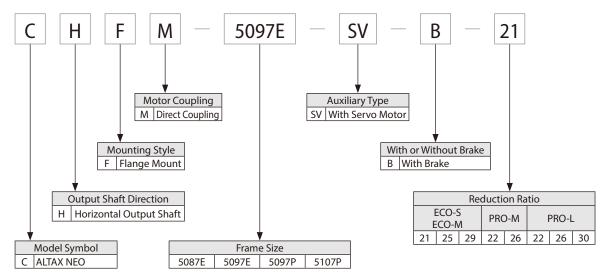
The product has been tested and verified to work with the following controllers in communication mode.

- BlueBotics/Autonomous navigation system ANT lite⁺ (CANopen)
- Hitachi Industrial Equipment Systems Co., Ltd./Laser positioning system ICHIDAS, industrial controller HX series (RS-485 Modbus RTU)

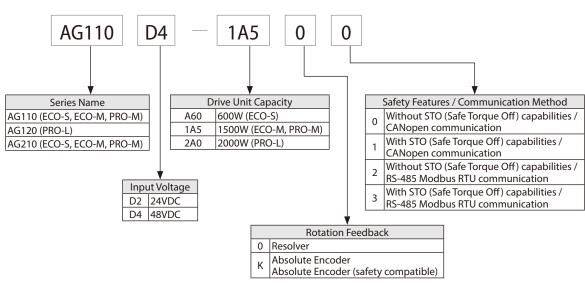
Contact us for further details.

Nomenclature

Gearmotor (Gear + Servo Motor)



Drive



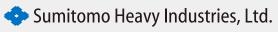




Smartris products use servo motors provided by Lafert S.p.A., an Italian industrial motor manufacturer that became part of the Sumitomo Heavy Industries Group in 2018. Lafert S.p.A. offers a wide range of electronic and control products, including high-efficiency magnet motors, induction motors, and servo motor drives, to meet customer needs in the fields of automation and energy.

Sumitomo Heavy Industries Group will continue to provide drive solutions that meet the sophisticated needs of society by mutually utilizing and integrating the technologies and knowledge of gearmotors, electronics, and control.

Specifications, dimensions, and other items are subject to change without prior notice.



Power Transmission & Controls Group Headquarter ThinkPark Tower, 1-1 Osaki 2-chome, Shinagawa-ku, Tokyo 141-6025, Japan

